national accelerator laboratory

TM-517 2200.000

AN ABSOLUTE | Bdl CALIBRATION OF B2 MAGNETS FOR THE AVB SYSTEM OF THE SINGLE ARM SPECTROMETER FACILITY

By M. Sogard and A. Weitsch

The change of scattering angle for the Single Arm Spectrometer (EAS) in the M6 beam line is done by magnetically deflecting the incident beam so that it passes at an angle through the H2 target. This is done by three Angle Varying Bends (AVB). (Figure 1) AVB1 is stationary, AVB2 can be moved remotely up and down, and AVB3 has a combined up down and tilting movement to follow the deflected beam. AVB2 and AVB3 have the same palority and are opposite to AVB1. The \$\int Bd1\$ of the system is proportional to the scattering angle and must be known with good precision.

The most important data are summarized in Table 1. In order to get an absolute calibration of ∫Bdl which relates to an easily monitored quantity in a reproducible way, we use a 3' Reference Magnet (AVBRef) in series as our standard. Before any measurement the magnets and AVBRef get degaussed to get them tracking. Above 12KG(-3000A) mainly AVBRef goes differently into saturation and tracking is lost. Our calibrations are only valid for B≤ 12KG This was verified to about 5 Gauss using a Rawson-Lush rotating coil put about 2' from one end into a magnet. The data are shown in Figure 2. Points beyond 12KG and coming back down from there clearly deviate.

To get the absolute calibration two different methods were tried. The magnet was measured on the test stand of the Fermilab magnet measurement group using their long flip coil. The integrator time constant was measured in three different ways agreeing and repeating perfectly. Also the integrated output voltage measurement was completely reliable. But the coil itself proved non-reproducible for the 10' magnets to better than 1%.

This two turn stretched wire coil was designed for measuring the 20' magnets. No definite cause could be found in the finite amount of time available. Therefore we resorted to map the field in the homogenous part every 2" using an NMR probe. The end fields were mapped with a Rawson-Lush rotating coil, taking measurements every 2cm. For the NMR measurement it was essential to put the probe into a 6"xl.75"x3.5"Cu bloc to cancel the power supply ripple by eddy currents. For ABV2 about 1/3 of the magnet stays unmapped due to the length of the probe cable. The measurements are displayed in Figure 3-8. Inside the homogeneous part field variations of t.1% are found, which result from random variations of the stacking of laminations. The ratio of the average field to the reference field is given in Table 1.

The mapping of the end fields was numerically integrated and expressed as $\Delta l = l_{mag} - l_{steel}$. Since the variations from one magnet to the next, most likely coming from small positioning erros, do not show as systematic differences on the plots of the end field, only one average value for each with and without mirror plate was finally used. Results are given in Table 1.

PREDICTIONS OF BEAM EXCURSION

The attached Fortran program was used to compute the various beam excursions, necessary field values in AVBRef and the height of a hodoscope in between AVB2 and AVB3 for various scattering angle θ and beam momenta.

There is a small residual steering effect (DYTGT) left at the center of the target, where the beam should cross the nominal beam line. This can be suppressed by using a shunt bypassing around AVB2 and AVB3 a fraction DII of the current. Results are given separately for DII=0 and DII≠0.

The approximation used to predict the current is good to about 1%. The field prediction is the primary number. Results of this calculation are given in Table 2 and 3. One should note that the beam steering is not only sensitive to the magnet calibration but also their placement.

We would like to thank the staff of the Fermilab magnet measurement group for their help with equipment and measurements.

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THIS PROGRAM IS ONLY TO PRINT A NICE TABLE
Ċ
      IOUT=7
               JP=50,200,50
          20
      DO
       P=FLOAT(JP)
       WRITE (TOUT, 101) P
        FORMAT (181,F10,1,6H GEV/C
  101
                     B/TH
                            HIVI
                                    DIVI
                                         HZ/TH
                                                  H3/TH HHD/TH AL3/TH AHD/T
        70HOTHETA
     2H DYTGI
                     G/MR
                            AMR
                                     * %
                                         MILZMR MILZMR MILZMR
        70H
           MIL
       nn 10 lai,40
       THETA=FLOAT(1-7)*4./1000.
       IF (THETA EQ. Ø.) GOTO 10
       CALL AVB (THETA.P.BREF.CAVR.DCAVB.HAVB2.HAVB3.HHOD.ALF3.THHOD.Z)
       DCAVB=100. +DCAVB/CAVB
       IF (ABS(BREF), GT. 18.) GOTO 10
       BREFERREF/MUETA
       CAVB=CAVB/THETA
       CAVB=CAVB/1000.
       HAVB2=HAVR2/THETA
       HAV83=HAVR3/THETA
       HHOD=HHOD/THETA
       ALEXALEXATHETA
       THHOD=THHOD/THETA
       THETA=THETA+1000.
       WRITE (10HT, 100) THETA, BREE, CAVB, DCAVB,
                          HAVB2, HAVB3, HHOD,
                          ALF3, THHOD, Z
  100 FORMAT (140, F5, 1, F7, 2, F7, 2, F7, 3, 3F7, 2, 2F7, 4, F7, 1
   10
       CONTINUE
      CONTINUE
  20
       END
       SUBROUTING AVB (THETA, P, BRFF, CAVB, DCAVB, HAVB2, HAVB3, HHOD,
                       ALF3, THHOD, ZERO)
      REAL AL (3), POS(4), L(4), DLI (3), BL (3)
       DATA AL/128.41,238.64,119.42/.
             POS/1410.974.1443.849.1462.578.1455.691/,
     1
             POSTGT/1469.858/, BEAMTH/0.006/
     2
       DATA_ ICALLYU/
      IF (ICALL, ME. 0) GOTO 100
       HODO IS 4.3 IN DWN OF POS(4)=CENTER OF GAP
C
       POS(4) = POS(4) + 4.3/12.
       DO 10 1=1.4
   10 L([)=-(POS([)-POSTGT)+12./COS(BEAMTH)
C
      CONTINUE
     TOTAL NEEDED BENDPOWER IN KGAUSS*INCH
       SIBDL=PATHETA/0.00915
       SIBOL=SIBOL*12.
       CORRECT FOR ACTUAL LENGTH IN MAGNET DUE TO CURVED TRAJECTORY
C
       USE SIN(X)=X-X++3/6 AND RATIO OF BEND ANGLES 1:2:1
C
        DLL(1)=THETA++2/24.
        DLL(2) = D(1 (1)
        DLL(3) = D(1 (1)/4.
       CORRECTION FOR MOVEMENT OF AVB3 ALONG Z AXIS
       PIVOT TO CENTER DY=18.7 IN.DZ=26 IN AND ALF3=.75*THETA
       DL39THETA+(14,01+7,3+THETA)
       しくる)=しくる)=かしる。
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1.	DO 110 [=1,3 10 BL(I)=AL(I)+(1,+DLL(I))
Ġ Ġ	NO STEERING CONDITION AT TARGET FRACTIONAL CURRENT DIT BYPASSING AVB2+3, IF NEGATIVE BYPASSING AVB1 IF THERE IS NO SHUNT SET DIT=0. DIT=(BL(2)*L(2)+BL(3)*L(3)-BL(1)*L(1))/(BL(2)*L(2)*BL(3)*L(3))
С	DÎÎ= 0. REQUIRED FIELD IN REFERENCE MAGNET BREF=SIRDI/(-BL(1)+(1DIÎ)+(BL(2)+BL(3)))
Č	ACTUAL BEND ANGLES BL AND TAN OF BEAMANGLE AFTER MAGNETS THEBREF THETA/SIBOL BL(1)=BL(1)+TH
	BL(2)=BL(2)*TH*(1DII) BL(3)=BL(3)*TH*(1DII) T1=SIN(BL(1))/COS(BL(1))
	T12=SIN(B)(1)-BL(2))/COS(RL(1)-BL(2)) T123=SIN(R)(1)-BL(2)-BL(3))/COS(BL(1)-BL(2)-BL(3)) ZERO IS VERT MISSTERING AT TARGET ZERO=T1*(I(1)-L(2))*T12*(I(2)-L(3))*T123*L(3)
	ZERO=ZERO±1000. ALF3=THETA-BL(3)/2. THHOD=THETA-BL(3)
	HEIGHTS TO WHICH TO SET MAGNETS AND HODO HAVB2=T1*(1(1)-L(2)-AL(2)/2.)+AL(2)*BL(2)/16. HAVB3=T1*(1(1)-L(2))+T12*(L(2)-L(3)-AL(3)/2.)
	HAVB3=HAVB3+BL(3)+AL(3)/16, HHOD=T1+(i(1)-L(2))+T12+(L(2)-L(4)) ROUGH VALUE OF NEEDED CURRENT
	CAVB=BREF+1000,74,12 CAVB=CAVB+AMPF(CAVB) DCAVB=DII+CAVB
C	UN DO AVR3 MOVEMENT L(3)=L(3)+DL3 RETURN END
G	FUNCTION AMPFOD) SATURATION CURVE FOR A B2 MAGNET A=D/1000.
	ÎF (A.LE.2.) AMPF=1. IF (A.GT.2.) AMPF=1.+1.2F-4+A**3*(A-2.) RETURN END
<u> </u>	
10 mg/s	

TABLE 1

	AVB1	AVB2	AVB3	3'Ref Mag.	
Serial #	B2-10-3	2115	B2-10-2	B2-1X	
Length of Steel	120.00"	238.94"	119.875"	3'	
Power end	up stream	up stream	up stream	_	
Z of center +	1410.974'	1443.849'	1462.578'	- .	
X of center +	71.871'	71.675	71.564'	<u>-</u>	
Magnetic Mirror *	none	downstream	up & down stream	none	
B average/Bref	1.00057	.99905	1.00027	1	
Δ 1 power end	+.15"	.06"	22"	+	
Δ l no power end	+.25	24"	28(+.21")	_	ı
<pre>1 mag. = /Bdl/B average</pre>	120.40"±.10"	238.75 ⁴ ±.10"	119.38"±.10"		S) I
l mag. eff = ∫Bdl/Bref	120.47"	238 53"	119.42"		

^{**} with the mirror plate taken off

^{*} steel plates 1.5"x30"x30"

⁺ in Meson Lab coordinate system

THETA	B/IH_	IVIH	DIVI	<u> </u>	H3/TH	Propries of the paper of the pa	AL3/TH	AHDZTH	DYTGT
MŘ	G/MR	A/MR	*	MIL/MR	MILIMR	MIL/MR			MIL.
-24.0	275.29	66"82	-0.152	154,08	121.18	126154	2.7489	0.4979	6.3
-20.0	275.26	66.81	-0.160	154.06	121.12	126,51	0,7490	0.4979	0,2
-15.0	275.23	66:30	-0.167	154,05	121,06	126,49	0.7490	0,4979	0.1
-12.6	275.20	66,30	+Ø ₊ 175	154.03	121.01	126.46	Ø.749Ø	0.4979	0.0
=8.0	275.17	66.79	-0.183	154.01	120.95	126.43	0.7490	Ø.498Ø	Ø . Ø
÷4.0	275,13	66',78	-0.191	153,99	120.90	126.40	0.7490	Ø.4982	0.0
4.0	275.07	66,76	-0,207	153,96	120.79	126.35	0.7490	0.4989	-0.0
8.0	275.04	66.76	-0.215	153.94	120.73	126.32	0.7490	Ø.498Ø	-0.0
12.0	275,00	66,75	-0,223	153,93	120.68	126.30	0.7490	2,4981	-0.0
ŋ s , ā	274,97	66,74	-0,231	153.91	128,62	126,27	2.7490	Ø.4981	-0.1
20.0	274.93	66.73	-0.239	153.89	120,57	126.25	0.7491	0.4981	-0.2
24.7	274.95	66.72	-0.247	153,88	120.52	126.22	0.7491	Ø.4981	-0.3
28.0	274.86	66:71	-0.255	153.86	120.46	126.20	8.7491	0.4981	40.5
32.0	274.83	66.72	-0.263	153.85	120.41	126.17	0,7491	0.4982	-Ø.7
36.7	274.79	66.74	-0.272	153.84	120.35	126.15	0,7491	0.4982	-1.8
40.0	274,76	66:79	-0.280	153.82	120.30	126.12	0.7491	0.4982	-1.4
44.0	274.72	66.87	-0.288	153.81	120.25	126.19	0.7491	Ø.4982	-1.8
48.0	274.68	66,98	-0.297	153.80	122.19	126.08	0.7491	Ø.4983	~2.4
52.0	274.64	67.15	-0.305	153.78	120.14	126.05	Ø.7491	0.4983	
56.0	274.61	67.37	-0.314	153.77	120.08	126.03	0.7492	Ø.4983	~3.7
60.00	274,57	67.66	-0.322	153.76	120.03	126.01	0.7492	0.4983	-4.6
64.0	274.53	68,74	-0.331	153,75	119.98	125.99	0.7492	0.4984	-5.6 · · · · ·
	and the same of th								

1	THETA	— BYTH	LVTH	DIVI	-H2/IH	H3/IH	HHD/TH	AL3/TH	AHDZİH	DYIGI
	MR	G/MR	A/MR	*	MIL/MR	MIL/MR	MIL/MR		ericanis Alimente de la companya	Nil
	-24,6	55%,58	133,64	-0,152	154,08	121.18	126,54	0.7489	ø.4979	<i>6</i> .3
	-20.0	55%.52	133.62	-0.160	154.06	121.12	126.51	0.7490	0.4979	Ø.2
	-16.0	550.46	133.61	+0,167	154,05	121.26	126,49	0.7490	0.4979	911
	-12.0	557.40	133,59	-0.175	154.03	121.01	126.46	0.7490	0.4979	0.0
	-8.0	55%.33	133.58	-0.183	154.01	120,95	126.43	0.7490	0.498@	0.0
	.+4.0	1550°.27	133,56	-0,191	153,99	120.90	126.47	0.7490	0.4980	0.0
	4.0	557.14	133.53	-0.207	153.96	120.79	126.35	7.7490	0.4980	-0.0
	8.0	550.07	133.51	-0.215	153.94	120.73	126.32	0.7490	Ø.498Ø	-0.0
2.02	12.4	557,01	133,50	-0,223	153.93	120,68	126.30	0,7490	0.4981	-0.0
	16.14	549.94	133,50	-0,231	153.91	1,20,62	126.27	0.7490	0.4981	-0.1
	20.0	549.87	133.67	-0.239	153.89	120,57	126.25	0.7491	0.4981	-0.2
	24.0	549.80	134268	-0.247	153,88	120,52	126.22	9.7491	0.4981	#0.3
3 (4 (4 (4 (4 (4 (4 (4 (4 (4 (4 (4 (4 (4 (4 (28.7	549.73	134.88	-0.255	153.86	120,46	126.20	0.7491	0.4981	-0.5
	32.0	549,66	136.24	-0.263	153.85	120,41	126.17	0,7491	0.4982	-0.7

TABLE 2.3 DIE +0

150.0 GEV/C

THE TA	B/TH G/MR	market the second secon	DI/I	H2/TH		HHD/TH MIL/MR	AL3/TH	AHD/TH	DYTGT Mil
		280'43					0.7490	0.4979	0.2
-16.0	825.69	200.41	-0.167	154.05	121.06	126.49	0.7490	0.4979	Ø . 1
*42.0	825.60	500,39	-0.175	154.03	121,01	126.46	0.7490	0.4979	2.6
48.00	825,50	200 36	-0.183	154.01	120.95	126,43	0.7490	0.4980	
-4.2	825.40	200.34	-0.191	153.99	120.90	126.40	0.7490	0.4980	Ø,Ø
4.9	825,21	200:29	-0,207	153.96	120,79	126.35	0.7490	0.4980	-0.0
8.0	825,11	2000-27	-0.2 ₁ 5	153.94	120.73	126.32	0.7490	0.4980	-0.8
12.9	825.01	200138	-0.223	153.93	120.68	126.30	0.7490	Ø.4981	-Ø.2
16.0	824.91	201.17	-0,231	153,91	120.62	126,27	0.7490	0,4981	-0.1
20 0	804 <u>.</u> 80	223°58	-0.239	153.89	120.57	126,25	0.7491	0.4981	30. 2

0

	2 803	0.0	CVIO							
THE	A Ř	B/TH G/MR	1/TH A/WR	DI/I	H2/TH MIL/MR	H3/TH MIL/MR	250 250 250 250 250 250 250 250 250 250	<u> </u>	HIVOHA	DYIGI MIL
	91 1	ØØ↓ 9 2	267,21	-0.167	154.05	121.06	126.49	0.7490	0.4970	#
-12.	Ø11	ØØ.79	267.18	-0.175	154.03	121.01	126.46	0.7490	0.4979	0,0
	Ø 11	07 . 67	267.15	-0.183	154.01	120.95	126,43	0.7490	0.4967	0.2
								0.7490		6.0
								0.7490		-0,0
1. Average			164 × 31 × 151		e artisti apara	35 M (45)		0.7490 0.7490	Astrophy (-0.0 -0.0
								Ø.749Ø		-0.1
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THETA MA		ALC: 100	Section 2011 Section Section 1997	HIL/MR	H3/IH MIL/MR	HHD/TH	AL3/TH	AHO/TH	MIL DAIRI
-24.0	275.0	2 66.97	0,000	154.41	121.70	27 M	0.7488	0.4975	2 2 2
-20.0	275,9	2 66.97	0.000	154.41	121.67	127.05	Ø.7487	0.4975	-11.3
-16.0					The a			0.4975	-9,5
-12:0	275.9 275.9		•					0.4975	<u>-7.5</u>
	275.9					127.05		Ø.4975	-5.2 -2.7
	275.9				43.46	127.05			
8.0	275.9	3 66,97	øø	154.41	121.47	127.05	0.7487	0.4975	6.1
12.12	275.9	2 466.97	0,200	154,41	121.45	127,05	7.7487	0.4975	9.5
	275,9					127,05			1 3. <u>1</u>
	275.9		0.000			127.05			16.9
	275.9 275.9	an ingle 27			es En Company	127.06 127.06			20,9 25.0
	275.9		0.000			127.06			29.4
	275.9	2 67',02	A D D D Own	154.42	121.29	127,06	9.7428	0.4975	33,9
40.0	275.9	<u>i 67''ø7</u>	0.000	154.43	121.26	127.07	0.7488	0.4975	38+6
	275.9					127.07			43.5
10 d 11 m 12 m 14 m 14 m 14 m 14 m 14 m 14 m		1 67,29 1 67,47						0.4975 0.4975	48.5
	275.9							Ø.4975	53.7 59.0
	275.9							0.4975	64.5
64.0	275.9	8 68,41	0.020	154.46	121.12	127.10	0.7488	Ø.4975	70.1

THEI	186		DIVI	H2/TH MIL/MA	H3/TH MIL/MR		AL3/TH	_AHD/TH	DYTGT	10
		4 133'04			121.70		0.7488	Ø.4975	-12.8	**************************************
-20.	ø 551.8	5 133,94	0.000	154.41	121.67	127.05	9.7487	Ø.4975	-11.3	
-16.	o 551. 8	5 133,94	0.000	154.41	121.64	127.05	2.7487	0.4975	-9.5	
-12.	Ø 551. 8	<u>5 133.94</u>	0.000	154,41	121.61	127.05	Ø.7487	Ø.4975	47 , B	
-8.	Ø 551.8	5 133.94	0.000	154.41	121.58	127.05	0.7487	0.4975	-5,2	٠
ar of section .	Z mi Seri	5 133.94	0,000	154.41	121.56	127.05	0,7487	0.4975	-2.7	
4.	a 55(,8	5-133.94	Ø,000	154.41	121,50	127,05	0.7487	0.4975	3.0	
8,	0 551.8	5 133.94	0.000	154.41	121.47	127.05	0.7487	0.4975	6.1	
12.	a 551.8	5 133,34	0.000	154,41	121.45	127.05	0.7487	0.4975	9.5	
16.	a 551.8	5 133.97	0,000	154.41	121.42	127.05	0,7487	Ø,4975	13,1	
20.	ø 551.8	5 134.15	0.000	154.41	121.39	127.05	0.7487	0.4975	16.9	
24,	Ø 551.8	4 134.59	0.000	154.41	121.37	127.06	0,7428	Ø.4975	20.9	18.0
and a	ø 551¦8	4 135,43	0.000	154.42	121.34	127.06	Ø,7488	0.4975	25.0	
32.	ø 551.8	4 136.83	0.000	154.42	121,31	127.06	Ø.7488	0.4975	29.4	

TABLE 3.3 DII=0

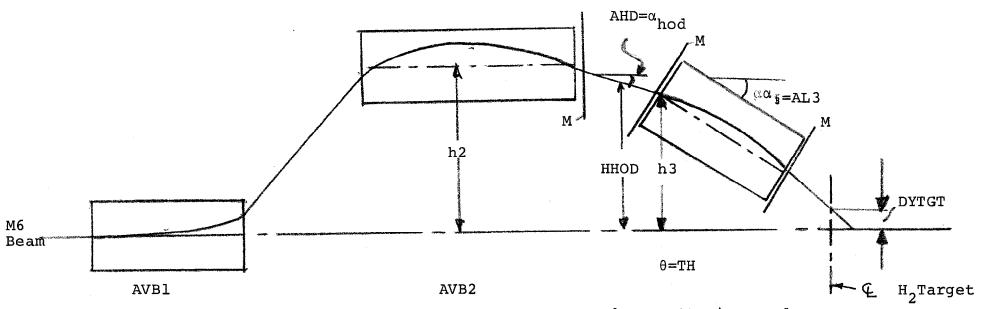
150.0 GEV/C

THETA	BVIH	1/14		H2/TH	H3/TH	HHD/TH	AL3/TH	AHD/IH	DYIGI
NA	a flaithis "Calland			MILIMR					MIL
<u>-20.10</u>	827.77	200.91	ø,baø	154.41	121-67	127.05	9.7487	0.4975	-11.3
-16.0	827.77	200.92	0.000	154.41	121.64	127.05	0.7487	0.4975	-9.5
-12.0	827,77	200192	0,000	154.41	121.61	127.05	0.7487	0.4975	-7. 5
*****	827.78	200",92	0.000	154,47	121.58	127.05	2.7487	0.4975	15.2
-4.0	827.78	200.92	0.000	154.41	121.56	127.05	0.7487	0.4975	-2.7
4.2	827.78	200.92	0.000	154.41	121,50	127.05	0.7487	0.4975	3.0
8,7	827.78	200.92	0,000	154.41	121.47	127.05	0.7487	0.4975	
12.9	827.77	201.05	0.000	154.41	121.45	127.05	0.7487	0.4975	9 . 5
16.9	827.77	201.89	0,000	154,41	121.42	127.05		0,4975	13.4
30.a	857 77	204"47	0.000	154,47	121 39	127,05	0,7487	0.4975	14.9

200.0 GEV/C

		Y . U							
THETA	B/TH G/MR	I/TH A/MR	n1/1	H2/TH		HHD/TH MIL/MR	AL3/TH	AHD/TH	DYTGT
MA							epart i statistica della seconda della secon		
-16.0110				154.41					<u> </u>
-12.0116	-			154.41					-7.5
8,0110	13.70	267.89	0.000	154.41	121.58	127.05	0.7487	0.4975	-5.2
-4.011	13.70	267'39	0,000	154.41	121.56	127.05	0.7487	0.4975	22.7
4.0119	3.70	267.89	ଡ.ଅମଡ	154.41	121,50	127.05	0,7487	0.4975	3,0
8,711	/3 , 7ø	267,93	0.000	154.41	121,47	127,05	0.7487	0.4975	6.1
12.0114	3.70	259]]19	0.000	154,41	121,45	127.05	0.7487	0.4975	9.5
16.0110	3.70	273.67	0.000	154.41	121.42	127.05	0.7487	0.4975	13.1
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Figure 1

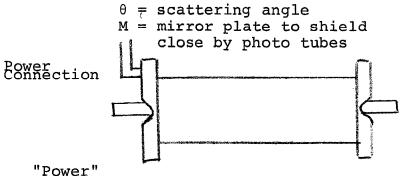


 α_{3} = tilt of AVB3

hod = tilt of beam in hodoscope between AVB2 and AVB3

h₃= excursion of AWB3 at upstream edge of steel

M = magnetic mirror plate 1.5"x30"x30"



"Power" End

"non power end"

